

# On the Regularity of the Landweber Transform

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# Nonexpansive and Quasi-Nonexpansive Operators

## Definition

Let  $\mathcal{H}$  be a Hilbert space. We say that an operator  $T : \mathcal{H} \rightarrow \mathcal{H}$  is:

*nonexpansive* (NE), if

$$\forall_{x,y \in \mathcal{H}} \quad \|Tx - Ty\| \leq \|x - y\|;$$

*$\alpha$ -averaged*,  $\alpha \in (0, 1)$ , if  $T = \alpha S + (1 - \alpha) \text{Id}$  for a NE operator  $S$ ;

*firmly nonexpansive* (FNE), if  $T$  is  $\frac{1}{2}$ -averaged;

*quasi-nonexpansive* (QNE), if

$$\forall_{x \in \mathcal{H}, z \in \text{Fix } T \neq \emptyset} \quad \|Tx - z\| \leq \|x - z\|;$$

*$\rho$ -strongly quasi-nonexpansive* ( $\rho$ -SQNE), where  $\rho > 0$ , if

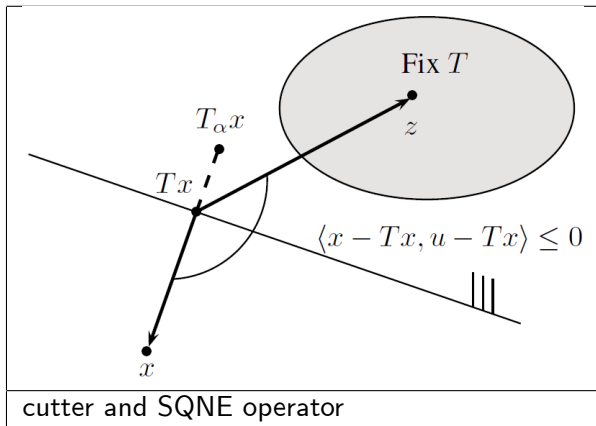
$$\forall_{x \in \mathcal{H}, z \in \text{Fix } T \neq \emptyset} \quad \|Tx - z\|^2 \leq \|x - z\|^2 - \rho \|Tx - x\|^2;$$

a *cutter* if

$$\forall_{x \in \mathcal{H}, z \in \text{Fix } T \neq \emptyset} \quad \langle z - Tx, x - Tx \rangle \leq 0;$$

( $\Leftrightarrow T$  is 1-SQNE).

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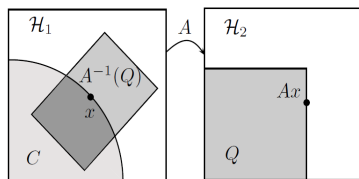


# Split Feasibility Problem and the Landweber Transform

$\mathcal{H}_1$  and  $\mathcal{H}_2$  - two real Hilbert spaces,  $A : \mathcal{H}_1 \rightarrow \mathcal{H}_2$  a bounded linear operator. The *Split Feasibility Problem* (SFP) is to

find  $x \in C$  such that  $Ax \in Q$ ,

where  $C \subseteq \mathcal{H}_1$  and  $Q \subseteq \mathcal{H}_2$  are closed and convex.



SFP with  $\mathcal{H}_1 = \mathbb{R}^n$  and  $\mathcal{H}_2 = \mathbb{R}^m$  was introduced by Censor and Elfving in 1994.

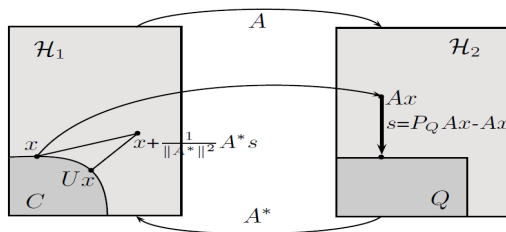
# Split Feasibility Problem and the Landweber Transform

In 2002 Byrne proposed the following *CQ-method* (in a finite dimensional case)

$$x^{k+1} = P_C(x^k + \frac{\lambda}{\|A\|^2} A^T (P_Q Ax^k - Ax^k)),$$

where  $\lambda \in (0, 2)$  and  $\|A\|$  is the spectral norm of  $A$ , and proved its convergence to

$$\underset{x \in C}{\text{Argmin}} \frac{1}{2} \|P_Q(Ax) - Ax\|^2 \quad (= \text{Fix}(\text{Id} + A^T (P_Q - \text{Id})A)).$$



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If  $Q = \{b\} \subseteq \mathcal{H}_2$  then the SFP is to find  $x \in C$  with  $Ax = b$ . In this case the CQ-method is called the *projected Landweber method*.

Replace  $P_C$  and  $P_Q$  in the CQ-method by sequences of QNE operators  $S_k$  and  $T_k$  and the parameter  $\lambda$  by a sequence  $\lambda_k \in (0, 1)$

$$x^{k+1} = S_k(x^k + \frac{\lambda_k}{\|A\|^2} A^*(T_k(Ax^k) - Ax^k)). \quad (1)$$

We introduce a *Landweber transform* denoted by  $\mathcal{L}_A\{\cdot\}$  or shortly  $\mathcal{L}\{\cdot\}$ , which for a given operator  $T : \mathcal{H}_2 \rightarrow \mathcal{H}_2$  assigns an operator  $\mathcal{L}\{T\} : \mathcal{H}_1 \rightarrow \mathcal{H}_1$  defined by

$$\mathcal{L}_A\{T\} := \text{Id} + \frac{1}{\|A\|^2} A^*(T - \text{Id})A$$

which we call a *Landweber operator* (related to  $T$ ).

Denoting  $U_\lambda := \text{Id} + \lambda(U - \text{Id})$  – the  *$\lambda$ -relaxation* of  $U$ , we write (1) as:

$$x^{k+1} = S_k \mathcal{L}\{(T_k)_{\lambda_k}\}$$

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- ③ C.–Reich–Zalas, 2020: Conditions for the weak / strong / linear convergence.

## Definition (Bauschke–Borwein, 1996)

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  - If  $\dim \mathcal{H} < \infty$ , then  $\mathcal{C}$  is boundedly regular;
  - If all  $C_i$ ,  $i \in I$ , are half-spaces, then  $\mathcal{C}$  is linearly regular;

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- The metric projection  $P_C$  is linearly regular.

# Regular Families of Sets and Regular Operators

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- Let  $U: \mathcal{H} \rightarrow \mathcal{H}$  be strongly quasi-nonexpansive,  $x^0 \in \mathcal{H}$  and

$$x^{k+1} := Ux^k, k \geq 0.$$



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# Regular Families of Sets and Regular Operators

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- The theorem is also true if we replace  $U$  by a sequence of operators  $U_k$ . In this case one should define a (weakly, linearly) regular sequence operators.

# Properties of the Landweber Operator

$$\mathcal{L}\{T\} := \text{Id} + \frac{1}{\|A\|^2} A^*(T - \text{Id})A$$

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  - In particular, if  $T$  is a cutter then  $\mathcal{L}\{T\}$  is also a cutter.

## Theorem

- Let  $A : \mathcal{H}_1 \rightarrow \mathcal{H}_2$  be nonzero bounded linear,  $T : \mathcal{H}_2 \rightarrow \mathcal{H}_2$  be QNE with  $\text{im } A \cap \text{Fix } T \neq \emptyset$ , and  $\mathcal{L}\{T\} : \mathcal{H}_1 \rightarrow \mathcal{H}_1$  be the Landweber operator, defined by

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# Extrapolated Landweber Operator

Let  $T : \mathcal{H}_2 \rightarrow \mathcal{H}_2$ , and  $\sigma : \mathcal{H}_1 \rightarrow [1, \infty)$  be an *extrapolation function*.

## Definition

The operator  $\mathcal{L}_\sigma\{T\} : \mathcal{H}_1 \rightarrow \mathcal{H}_1$ , defined by

$$\mathcal{L}_\sigma\{T\}x := x + \sigma(x)(\mathcal{L}\{T\}x - x), \quad (2)$$

is called an *extrapolated Landweber operator* (related to  $\sigma$ ).

## Theorem (C., 2016, C.–Reich–Zalas, 2020)

Let  $T$  be QNE,  $\text{Fix } \mathcal{L}\{T\} \neq \emptyset$  and the extrapolation function  $\sigma$  satisfies

$$\sigma(x) \leq \frac{\|A\|^2 \cdot \|T(Ax) - Ax\|^2}{\|A^*(T(Ax) - Ax)\|^2} \text{ for all } x \in \mathcal{H}_1 \quad (3)$$

Then  $\mathcal{L}_\sigma\{T\}$  is QNE. Conditions for weak/strong/linear regularity of  $\mathcal{L}_\sigma\{T\}$  are similar to those of  $\mathcal{L}\{T\}$ .

# Projected Extrapolated Landweber Method

Let  $S, T$  be QNE,  $F := \text{Fix } S \cap \text{Fix } \mathcal{L}\{T\} \neq \emptyset$ ,

$$x_0 \in \mathcal{H}_1, \text{ and } x_{k+1} = S_{\mu_k} \left( x_k + \lambda_k \frac{\sigma(x_k)}{\|A\|^2} A^* T(Ax_k) - Ax_k \right), \quad (4)$$

where  $\mu_k, \lambda_k \in [\varepsilon, 1 - \varepsilon]$  for some small  $\varepsilon > 0$  and  $\sigma$  satisfies

$$1 \leq \sigma(x) \leq \frac{\|A\|^2 \cdot \|T(Ax) - Ax\|^2}{\|A^*(T(Ax) - Ax)\|^2} \text{ for all } x \in \mathcal{H}_1.$$

## Theorem (C.–Reich–Zalas, 2020)

Let  $x^k$  be given by (4).

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# Linear Split Feasibility Problem

Find  $x \in \mathbb{R}^n$  with  $Ax \in Q$

where  $A$  is an  $m \times n$  matrix with nonzero rows  $a_i \in \mathbb{R}^n$  and  $Q := \{y \in \mathbb{R}^m : y \leq b\}$ .

- Simultaneous projection for the system  $Ax \leq b$

$$P(x) := \sum_{i=1}^m w_i \left( x - \frac{(a_i^T x - b_i)_+}{\|a_i\|^2} a_i \right),$$

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- $P(x)$  can be written in a matrix form

$$P(x) = x - A^T D (Ax - b)_+,$$

where  $D := WN^{-2}$ ,  $W := \text{diag } w$ ,  $N := \text{diag}(\|a_1\|, \|a_2\|, \dots, \|a_m\|)$ .

Clearly,

$$D = \text{diag}\left(\frac{w_1}{\|a_1\|^2}, \frac{w_2}{\|a_2\|^2}, \dots, \frac{w_m}{\|a_m\|^2}\right).$$



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$$\mathcal{L}_{D^{\frac{1}{2}}A}\{P_{Q'}\}(x) = x - \frac{1}{\lambda_{\max}(A^T DA)} A^T D(Ax - b)_+,$$

where  $Q' := \{y \in \mathbb{R}^m : y \leq D^{\frac{1}{2}}b\}$ , and is not equivalent in general to  $\mathcal{L}_A\{P_Q\}(x)$ .

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- Let  $w \in \Delta_m$  and  $I(w) := \{i : w_i > 0\}$ . It holds

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- $\lambda_{\max}(A^T DA) = 1$  if and only if the system  $\mathcal{A}(w) := \{a_i : i \in I(w)\}$  is collinear, i.e.,  $a_i = \alpha_i a_1$  for some  $\alpha_i$ ,  $i \in I(w)$ .

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  - If  $\lambda_{\max}(A^T DA) = w_j$  then  $a_j$  is orthogonal to all  $a_i$ ,  $i \in I(w)$ ,  $i \neq j$ ;
  - If the system  $\{a_i : i \in I(w)\}$  is orthogonal then  $\lambda_{\max}(A^T DA) = w_j$ ;
  - $\lambda_{\max}(A^T DA) = 1$  if and only if the system  $\mathcal{A}(w) := \{a_i : i \in I(w)\}$  is collinear, i.e.,  $a_i = \alpha_i a_1$  for some  $\alpha_i$ ,  $i \in I(w)$ .

## Corollary

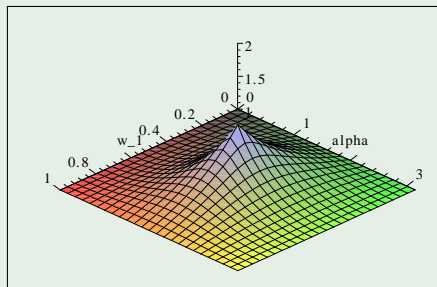
- The Landweber operator  $\mathcal{L}_{D^{\frac{1}{2}}A} \{P_{Q'}\}$  is an extrapolation of the simultaneous projection operator  $P$ . Moreover, if the system  $\mathcal{A}(w)$  is not collinear then  $\mathcal{L}_{D^{\frac{1}{2}}A} \{P_{Q'}\}$  is a strict extrapolation of  $P$ .

# Linear Split Feasibility Problem

## Example

$m = 2$ ,  $A$  has normed rows  $a_1, a_2$  and  $w = (w_1, 1 - w_1)$ ,  $w_1 \in [0, 1]$ ,  
 $\alpha = \angle(a_1, a_2)$ .

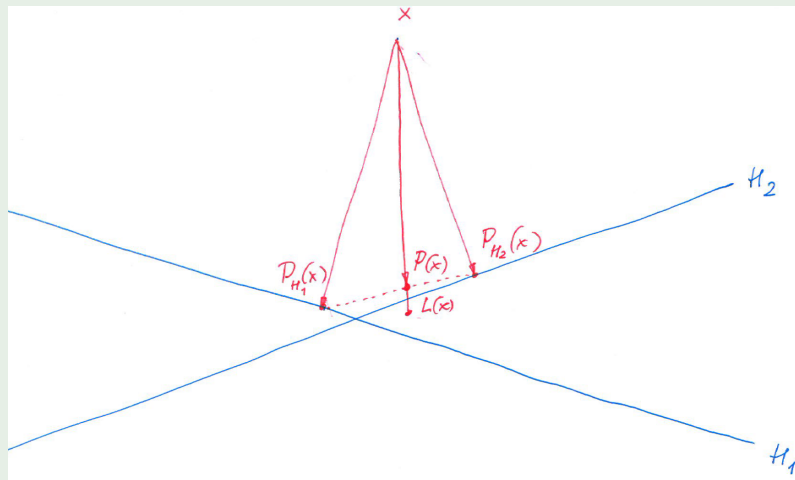
$$\lambda_{\max}(A^T D A) = (1 + \sqrt{1 - 4w_1(1 - w_1) \sin^2 \alpha})/2.$$



The extrapolation parameter  
 $\sigma = \frac{1}{\lambda_{\max}(A^T D A)}$  as a function of  
the weight  $w_1$  and the angle  $\alpha$

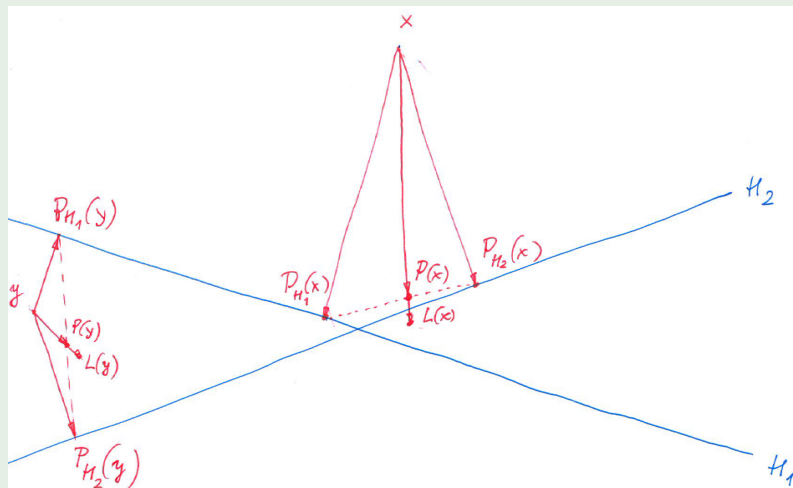
# Linear Split Feasibility Problem

## Example (continuation)



# Linear Split Feasibility Problem

## Example (continuation)

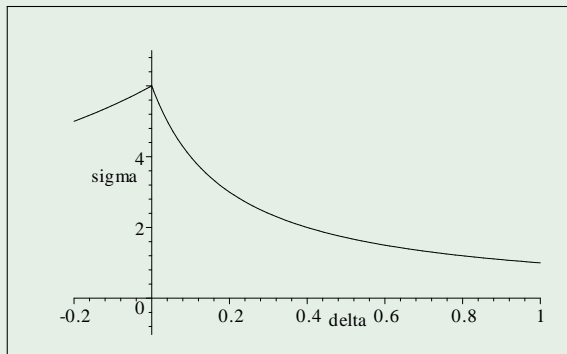




# Linear Split Feasibility Problem

## Example

$A$  – an  $m \times n$  matrix with normed rows  $a_i$ , and  $\delta := a_i^T a_j$ ,  $i \neq j$ ,  
 $w_i = \frac{1}{m}$ ,  $i = 1, 2, \dots, m$ .



The extrapolation parameter  $\sigma := \frac{1}{\lambda_{\max}(A^T D A)}$  as a function of  $\delta$  for  
 $m = 6$

# Extrapolated Landweber Operator for Linear Inequalities

- Let the extrapolation function  $\sigma : \mathbb{R}^n \rightarrow \mathbb{R}_+$  be defined by

$$\sigma(x) = \begin{cases} \frac{(Ax-b)_+^T D(Ax-b)_+}{\|A^T D(Ax-b)_+\|^2} & \text{if } Ax \not\leq b \\ 1 & \text{if } Ax \leq b \end{cases}$$

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- Then  $\sigma(x) \geq \frac{1}{\lambda_{\max}(A^T D A)} \geq 1$  and the operator

$$U_D(x) = x - \sigma(x) A^T D(Ax - b)_+$$

is an extrapolation of the Landweber operator

$$\mathcal{L}_{D^{\frac{1}{2}} A} \{P_{Q'}\}(x) := x - \frac{1}{\lambda_{\max}(A^T D A)} A^T D(Ax - b)_+$$

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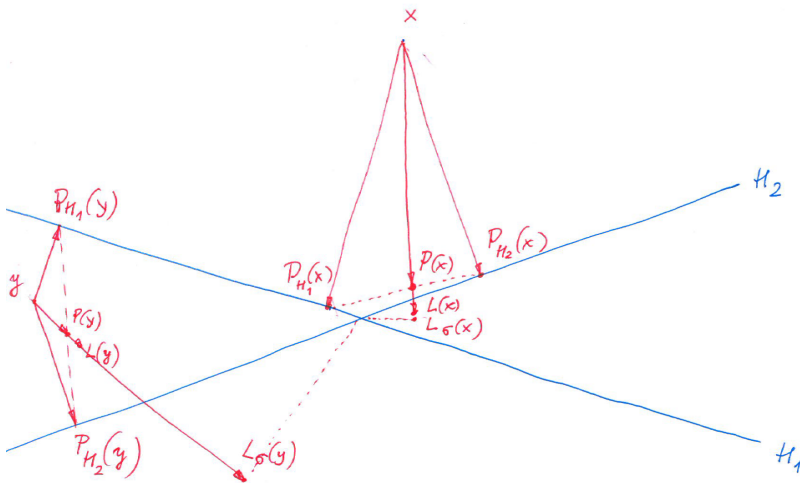
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- $V_D x$  is a linearly regular cutter. Thus, for any  $\lambda \in (0, 2)$  the method













$$x^{k+1} = U_{D,\lambda}(x^k)$$

converges linearly to a solution of  $Ax \leq b$ .

# Extrapolated Landweber Operator for Linear Inequalities



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Thank you for your attention!